AUTOMOTIVE CURRENT TRANSDUCER
HAH1DR 800-S

Introduction

The HAH1DR family is for the electronic measurement of DC, AC or pulsed currents in high power automotive applications with galvanic isolation between the primary circuit (high power) and the secondary circuit (electronic circuit).

The HAH1DR family gives you the choice of having different current measuring ranges in the same housing (from ± 200 A up to ± 900 A).

Features

- Open Loop transducer using the Hall effect
- Unipolar + 5 V DC power supply
- Primary current measuring range up to ± 800 A
- Maximum rms primary current limited by the busbar, the magnetic core or the ASIC temperature T° < + 150°C
- Operating temperature range: - 40°C < T° < + 125°C
- Output voltage: full ratiometric (in sensitivity and offset)
- Compact design.

Advantages

- Excellent accuracy
- Very good linearity
- Very low thermal offset drift
- Very low thermal sensitivity drift
- Wide frequency bandwidth
- No insertion losses.

Automotive applications

- Battery monitoring
- Starter Generators
- Inverters
- HEV application
- EV application.

Principle of HAH1DR Family

The open loop transducers use an Hall effect integrated circuit.

The magnetic flux density **B**, contributing to the rise of the Hall voltage, is generated by the primary current I_P to be measured.

The current to be measured I_P is supplied by a current source i.e. battery or generator (Fig. 1).

Within the linear region of the hysteresis cycle, **B** is proportional to:

$$B \ (I_P) = \text{constant (a)} \times I_P$$

The Hall voltage is thus expressed by:

$$V_H = (R_H/d) \times I \times \text{constant (a)} \times I_P$$

Except for I_P, all terms of this equation are constant. Therefore:

$$V_H = \text{constant (b)} \times I_P$$

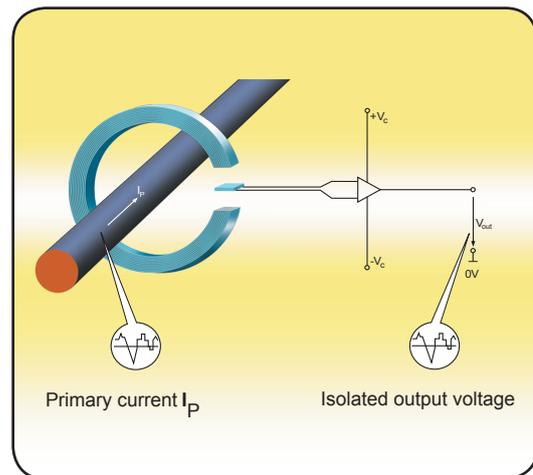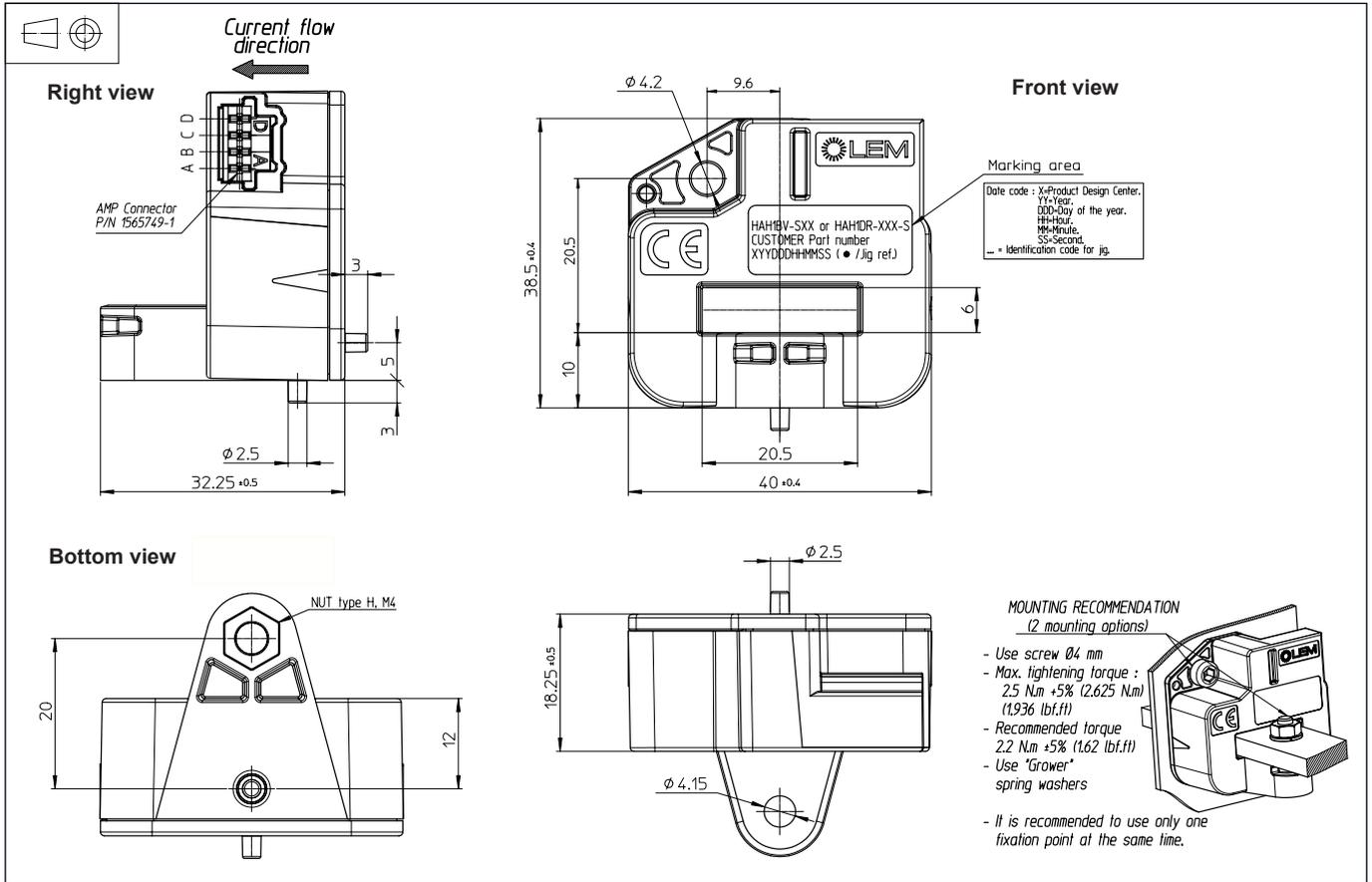The measurement signal V_H amplified to supply the user output voltage or current.

Fig. 1: Principle of the open loop transducer

HAH1DR 800-S

Dimensions HAH1DR family (in mm. 1mm = 0.0394 inch)

Right view

Current flow direction

AMP Connector P/N 1565749-1

A B C D

3

Ø 2.5

32.25 ±0.5

5

3

Front view

Ø 4.2

9.6

38.5 ±0.4

20.5

10

6

20.5

40 ±0.4

Marking area

Date code : X=Product Design Center.
YY=Year.
DDD=Day of the year.
HH=Hour.
MM=Minute.
SS=Second.
... = Identification code for jig.

HAH1BV-SXX or HAH1DR-XXX-S
CUSTOMER Part number
XYYDDDHHMMSS (● / Jig ref.)

Bottom view

NUT type H, M4

20

12

Ø 4.15

Ø 2.5

18.25 ±0.5

MOUNTING RECOMMENDATION
(2 mounting options)

- Use screw Ø4 mm
- Max. tightening torque :
  2.5 N.m ±5% (2.625 N.m)
  (1.936 lbf.ft)
- Recommended torque
  2.2 N.m ±5% (1.62 lbf.ft)
- Use "Grower"
  spring washers

- It is recommended to use only one
  fixation point at the same time.

Bill of materials

- Plastic case   PBT GF 30
- Magnetic core   Iron silicon alloy
- Pins   Brass tin platted
  Weight   48 g

Remarks

- $V_{OUT} > \dfrac{V_c}{2}$ when I_P flows in the direction of the arrow.

System architecture
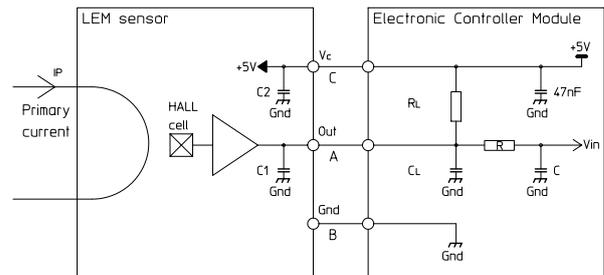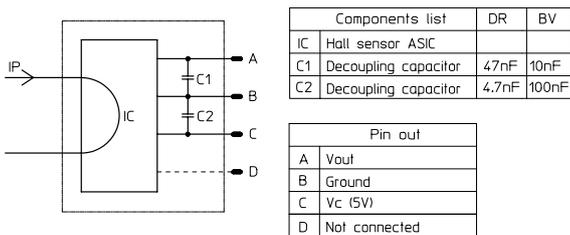

Components list		DR	BV
IC	Hall sensor ASIC		
C1	Decoupling capacitor	47nF	10nF
C2	Decoupling capacitor	4.7nF	100nF

Pin out	
A	Vout
B	Ground
C	Vc (5V)
D	Not connected

System architecture (example)

R_L >10 kΩ optional resistor for signal line diagnostic

V_{OUT}	Diagnosis
Open circuit	$V_{IN} = V_C$
Short GND	$V_{IN} = 0V$

C_L < 100 nF EMC protection
R_C Low pass filter EMC protection (optional)

HAH1DR 800-S

Absolute maximum ratings

Parameter	Symbol	Unit	Min	Typ	Max	Conditions
			Specification			
Electrical Data						
Max primary current peak	I_{Pmax}	A			1)	
Supply continuous over voltage	V_C	V			7	Not operating
Reverse voltage 2)			-0.5			1 min @ T_A = 25°C
Output over voltage (continuous)	V_{OUT}	V	-0.5		V_C + 0.5	
Continuous output current	I_{OUT}	mA	-10		10	
Output short-circuit duration	T_c	min			2	
Rms voltage for AC isolation test	V_d	kV			2	50 Hz, 1 min
Isolation resistance	R_{IS}	MΩ	500			500 V - ISO 16750-2
Electrostatic discharge voltage	V_{ESD}	kV			2	JESD22-A114-B
Ambient storage temperature	T_S	°C	-55		125	

Operating characteristics

| Parameter	Symbol	Unit	Min	Typ	Max	Conditions
			Specification			
Electrical Data						
Primary current	I_P	A	-800		800	
Calibration current	I_{CAL}	A	-500		500	@ T_A = 25°C
Supply voltage	V_C	V	4.75	5.00	5.25	
Output voltage (Analog) 3)	V_{OUT}	V	$V_{OUT} = (V_C/5) \times (2.5 + G \times I_P)$			@ V_C
Sensitivity 3)	G	mV/A		2.5		@ V_C = 5 V
Current consumption	I_c	mA		15	20	@ V_C = 5 V, @ - 40°C < T_A < 125°C
Load resistance	R_L	KΩ	10			
Output internal resistance	R_{OUT}	Ω			10	DC to 1 kHz
Capacitive loading	C_L	nF	1		100	
Ambient operating temperature	T_A	°C	-40		125	Connector limited 105°C
Output drift versus power supply	$V_{OUT\,PS}$	%		0.5		
Performance Data						
Sensitivity error	ε_G	%	-1.0	± 0.5	1.0	@ T_A = 25°C @ I = I_{CAL}
			-2.0		2.0	@ T_A = 25°C @ I = I_P
Electrical offset current	I_{OE}			± 2.5		@ T_A = 25°C
Magnetic offset current	I_{OM}	A		± 1		@ T_A = 25°C, after ± I_P
Global offset current	I_O		-3.5		3.5	@ T_A = 25°C
Average temperature coefficient of V_{OE}	$TCV_{OE\,AV}$	mV/°C	-0.08	± 0.03	0.08	@ - 40°C < T° < 125°C
Average temperature coefficient of G	TCG_{AV}	%/°C	-0.035	± 0.02	0.035	@ - 40°C < T° < 125°C
Linearity error	ε_L	%	-1		1	@ V_C = 5 V @, T_A = 25°C, @ I = I_P
			-0.5		0.5	@ V_C = 5 V @, T_A = 25°C, @ I = I_{PCAL}
Response time to 90 % of I_{PN} step	t_r	µs		5	8	@ di/dt = 100 A/µs
Frequency bandwidth 4)	BW	kHz		30		@ -3 dB
Output clamping voltage min	V_{sz}	V			0.1	@ V_C = 5 V, T_A = 25°C
Output clamping voltage max			4.9			@ V_C = 5 V, T_A = 25°C
Output voltage noise peak-peak	$V_{no\,pp}$	mV			12	DC to 1MHz

Notes:
1) Busbar temperature must be below 150°C
2) Transducer not protected against reverse polarity.
3) The output voltage V_{OUT} is fully ratiometric. The offset and sensitivity are dependent on the supply voltage V_C relative to the following formula:

$$I_P = \left(V_{OUT} - \frac{V_C}{2} \right) \times \frac{1}{G} \times \frac{5}{V_C} \qquad \text{with G in (V / A)}$$
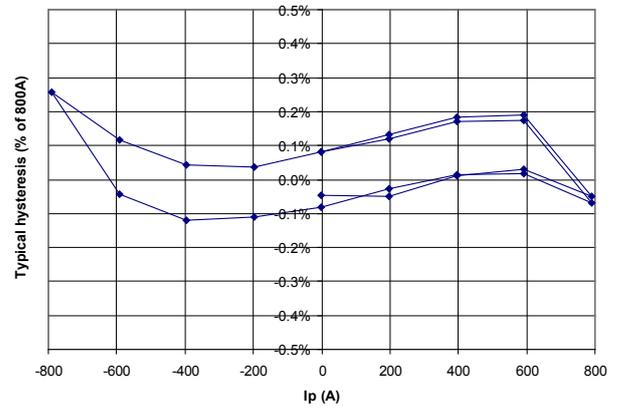
4) Tested only with small signal only to avoid excessive heating of the magnetic core.
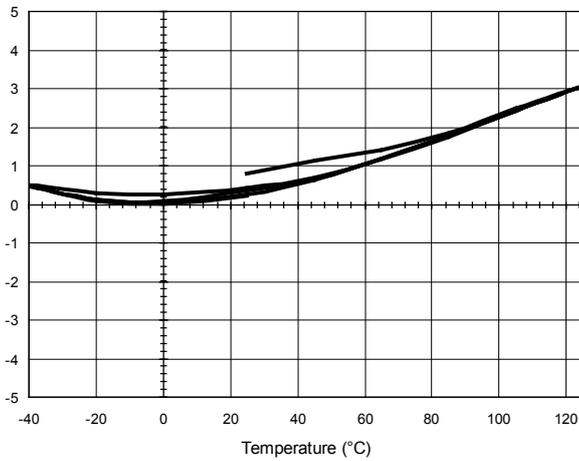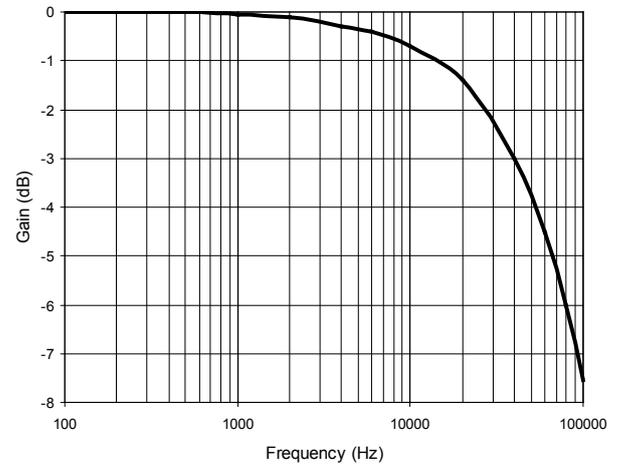
HAH1DR800-S : Typical Linearity (%)
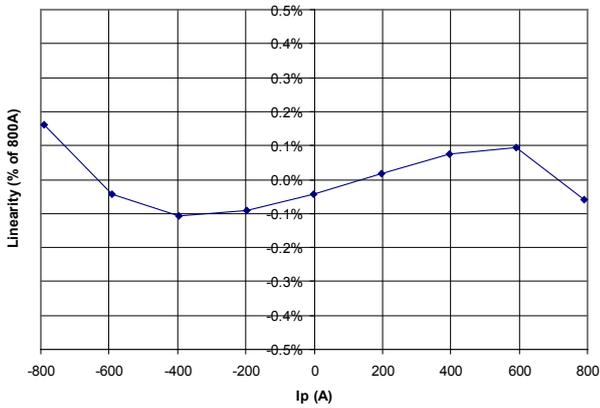
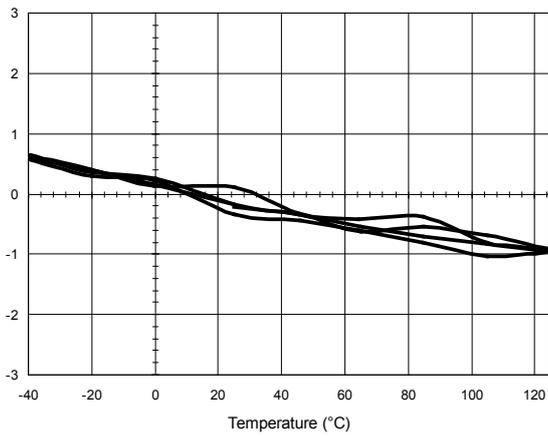## HAH1DR800-S : Typical Hysteresis (%)

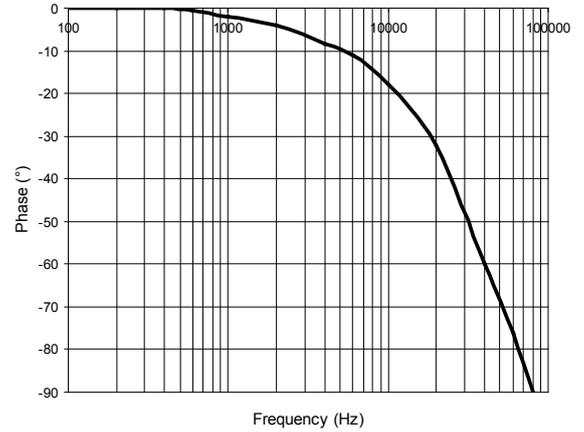## HAH1DR 800 Sensitivity Error (%)

HAH1DR 800 Frequency Bandwith

HAH1DR 800 Electrical offset Error (A)

HAH1DR 800 Phase

Typical response time at 100 A/µs

Channel 1 (yellow) : Primary current

Channel 2 (Red) :   Output voltage signal
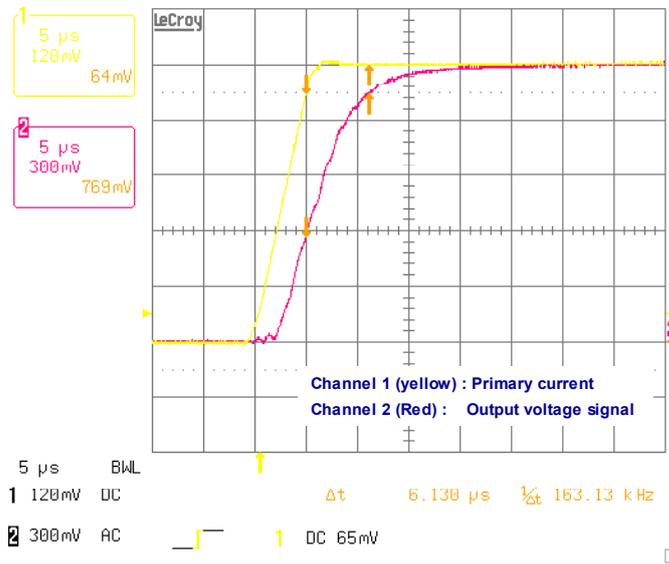
HAH1DR 800-S
PERFORMANCES PARAMETERS DEFINITIONS

Output noise voltage:

The output voltage noise is the result of the noise floor of the Hall elements and the linear I_C amplifier gain.

Magnetic offset:

The magnetic offset is the consequence of an over-current on the primary side. It's defined after an excursion of $I_{P\ max}$.

Linearity:

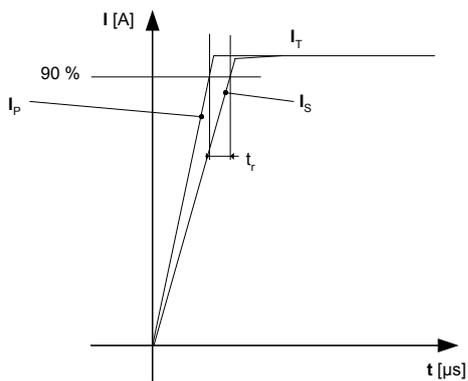The maximum positive or negative discrepancy with a reference straight line $V_{OUT} = f (I_P)$.

Unit: linearity (%) expressed with full scale of $I_{P\ max}$.

Linearity is measured on cycle + I_P, O, - I_P, O, + I_P without magnetic offset (average values used).
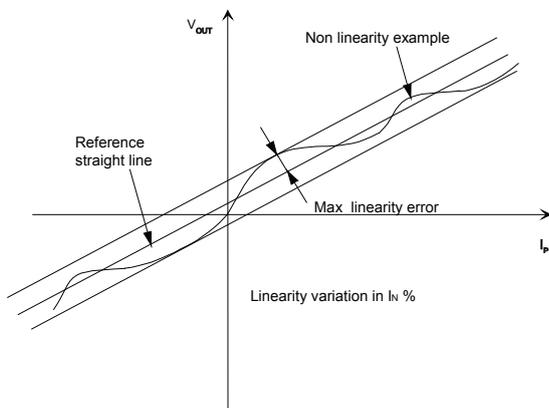
Response time (delay time) t_r:

The time between the primary current signal and the output signal reach at 90 % of its final value.

Typical:

Theorical value or usual accuracy recorded during the production.

Sensitivity:

The Transducer's sensitivity **G** is the slope of the straight line $V_{out} = f (I_P)$, it must establish the relation:

$V_{out} (I_P) = V_C/5 (G \times I_P + 2.5)$ (*)

(*) For all symetrics transducers.

Offset with temperature:

The error of the offset in the operating temperature is the variation of the offset in the temperature considered with the initial offset at 25°C.

The offset variation I_{OT} is a maximum variation the offset in the temperature range:

$I_{OT} = I_{OE}$ max - I_{OE} min

The Offset drift TCI_{OEAV} is the I_{OT} value divided by the temperature range.

Sensitivity with temperature:

The error of the sensitivity in the operating temperature is the relative variation of sensitivity with the temperature considered with the initial offset at 25°C.

The sensitivity variation G_T is the maximum variation (in ppm or %) of the sensitivity in the temperature range:

G_T = (Sensitivity max - Sensitivity min) / Sensitivity at 25°C.

The sensitivity drift TCG_{AV} is the G_T value divided by the temperature range.

Offset voltage @ I_P = 0 A:

Is the output voltage when the primary current is null. The ideal value of V_O is $V_C/2$ at V_C = 5 V. So, the difference of V_O -$V_C/2$ is called the total offset voltage error. This offset error can be attributed to the electrical offset (due to the resolution of the ASIC quiescent voltage trimming), the magnetic offset, the thermal drift and the thermal hysteresis.

Environmental test specifications

Name	Standard	Conditions
Damp heat, steady state	JESD22-A101	85°C - 85°C / 1000h
Isolation resistance	ISO 16750-2 § 4.10	500 V/1min
Temperature humidity cycle test	ISO 16750-4	-10 + 85°C 10 days
Isolation test	IEC 60664-1	2 kV/50 Hz/1min
Mechanical tests		
Vibration test (random)	IEC 60068-2-64 ISO 16750-3 & 4.1.2.5 (2007)	20 … 2000 Hz Random rms (11g rms) 8h/axis
Terminal strength test	According to LEM	
Thermal shocks	IEC 60068-214 Na	-40 + 125°C 300 cycles
Free fall	ISO 16750-3 § 4.3	1m concrete ground
EMC Test		
Radiated electromagnetic immunity	Directive 2004/104/CE ISO 11452-2	30 V/m 20-2000 MHz
Bulk current injection immunity	Directive 2004/104/CE ISO 11452-4	1-400 MHz - 60 mA
Radiated radio frequency electromagnetic field immunity	IEC 61000-4-3	80 MHz to 1,000 MHz - 10 V/m
Electrostatic discharge immunity test	IEC 61000-4-2	Air discharge=2 kV